

Discrete Time Control Systems 2nd Ogata Manual

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The time optimal control problem in unforced discrete systems is studied in this thesis. Comparison is made between the discrete and the continuous control systems by means of minimal-time isochrones. Concerning optimal time, it is shown that using discrete control system will take at most one

[On time-optimal second order discrete control systems](#)

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A comprehensive treatment of the analysis and design of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The book features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

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Discrete control systems, as considered here, refer to the control theory of discrete time Lagrangian or Hamiltonian systems. These discrete time models are based on a discrete variational principle, and are part of the broader field of geometric integration.

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Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller (μP), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC). $3 + - r(t) e(t)$ ADC μP DAC $u(t)$ Plant $y(t)$ 4

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Notes for Discrete-Time Control Systems (ECE-520) Fall 2010 by R. Throne The major sources for these notes are: † Modern Control Systems, by Brogan, Prentice-Hall, 1991. † Discrete-Time Control Systems, by Ogata, Prentice-Hall, 1995. † Computer Controlled Systems, by Aström and Wittenmark, Prentice-Hall, 1997.

[Notes for Discrete-Time Control Systems \(ECE-520\) Fall 2010](#)

First, digital computers are, by design, discrete-time devices, so discrete-time signals and systems includes digital computers. Second, almost all the important ideas in discrete-time systems apply equally to continuous-time systems. Alas, even discrete-time systems are too diverse for one method of analysis.

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Discrete-time control systems 2nd ed. This edition published in 1995 by Prentice-Hall International in London.

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The time interval between two discrete instants is taken to be sufficiently short that the data for the time between them can be approximated by simple interpolation. Discrete-time control systems differ from continuous-time control systems in that signals for a discrete-time control system are in sampled-data form or in digital form.

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(available) at all times. A typical continuous time control system is shown in Figure below. (Closed loop continuous-time control system) Discrete time Control System: Discrete time control systems are control systems in which one or more variables can change only at discrete instants of time. These instants, which may be denoted by kT ($k=0,1,2,\dots$)

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