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discusses the
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system shown in
Figure 1. It is
desired to
design a PID
controller G_c
(s) such that
the dominant
closed-loop

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poles are
located at $s =$
 $-1 \pm j 1$. For
the PID
controller,
choose $a = 0.5$,
and then
determine the
values of K and
 b . Draw a root
locus plot with
MATLAB. Figure 1
PID-controlled
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